Are encoders able to learn landmarkers for warm-starting of Hyperparameter Optimization?

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TLDR

The main problem that this work is trying to solve is the development of a tabular dataset encoder, which will produce representations that carry relevant information in the context of warm-starting Bayesian HPO.





Experiments

- Motivation
- One of AutoML's open problems is a measurement of tabular datasets similarity.
- Existing methods are based on predefined or learned meta-features, which often underperform against simple heuristics.
- Existing solutions are either too costly, yield minimal benefits, or lack proper evaluation.
- In this work, we attempt to solve Bayesian HPO's problem cold-start using novel dataset encoders.

Methods

We propose two novel methods of modeling tabular datasets similarity:

 The first solution relies on the deep metric learning of Dataset2Vec [1]. It aims to learn an encoder to produce such tabular dataset representations that their Figure 3. Flow of evaluation of each proposed approach

- As a baselines, we used a basic version of Dataset2Vec and simple heuristics for warm-starting HPO.
- We evaluated encoders in two ways: measurement of gains in the target meta-task and distance correlation between representations and distances between corresponding landmarkers.

Results

Results show that:

- Encoders managed to grasp information stored within landmarkers which can be seen in significant rank correlation between distances.
- However, our approaches did not provide significant gains in the warm-starting of the Bayesian HPO, which limits their practical applications.

Table 1. Rank correlations between encoders' outputs and landmarkers

Encoder	Average Stdev
Dataset2Vec basic	0.037 0.024

distances are close to distances between corresponding landmarkers.



Figure 1. Visualization of metric learning approach

 The second approach aims to reconstruct landmarkers. To achieve that, it first uses the Dataset2Vec encoder to produce a latent representation of the dataset, which is passed into the reconstruction network, which is simple MLP. As a loss function, this approach uses reconstruction error.



Dataset2Vec metric0.3320.030Dataset2Vec reconstruction0.1770.027



Figure 4. Comparison of objective values at the end of the initial phase



Figure 5. Comparison of objective values at the end of optimization

Discussion

Such results can be caused by:

- Noise induced by the Bayesian Optimization itself, which may not be able to sufficiently leverage initial configurations.
- Improper selection of the configurations contained in the portfolio.

Figure 2. Visualization of landmarker reconstruction approach

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References

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