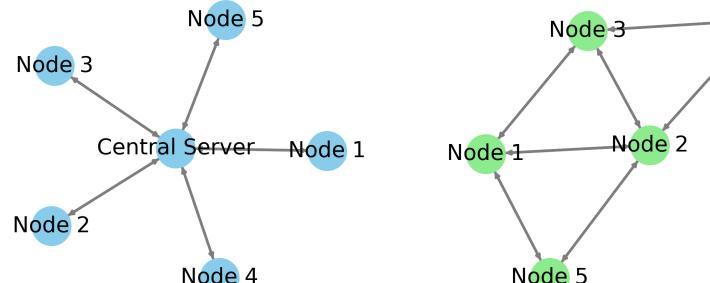
Carnegie Mellon University

Background

We work in a distributed learning scenario, where we have a set of agents that want to learn a common model without sharing their data. It is similar to federated learning, but there is no central node. We assume extreme imbalance case, where each client data from only 1 class.

Centralized Federated Learning

Distributed Learning



Usually, Parameter Space Regularization(PSR) is used to exchange information between models. If θ are model parameters, then it can be stated as: $\theta_i = \arg\min_{\theta_i} \|R_i(\theta_i) + \sum \lambda_{i,j} \|\theta_i - \theta_j\|^2$

Ongoing work at Auton lab proposes using Space Regularization(FSR) Function to exchange knowledge. If $f: \mathbb{R}^n \to \mathbb{R}^m$ is a machine leaning model, then i can be states as:

$$f_{i} = \arg\min_{f_{i}} \left(R_{i}(f_{i}) + \sum_{j=1}^{m} \lambda_{i,j} ||f_{i} - f_{j}||^{2} \right)$$

Objectives

Problem

 Although FSR outperforms PSR in non-iid settings it still performs much worse than a centralized model, in some cases

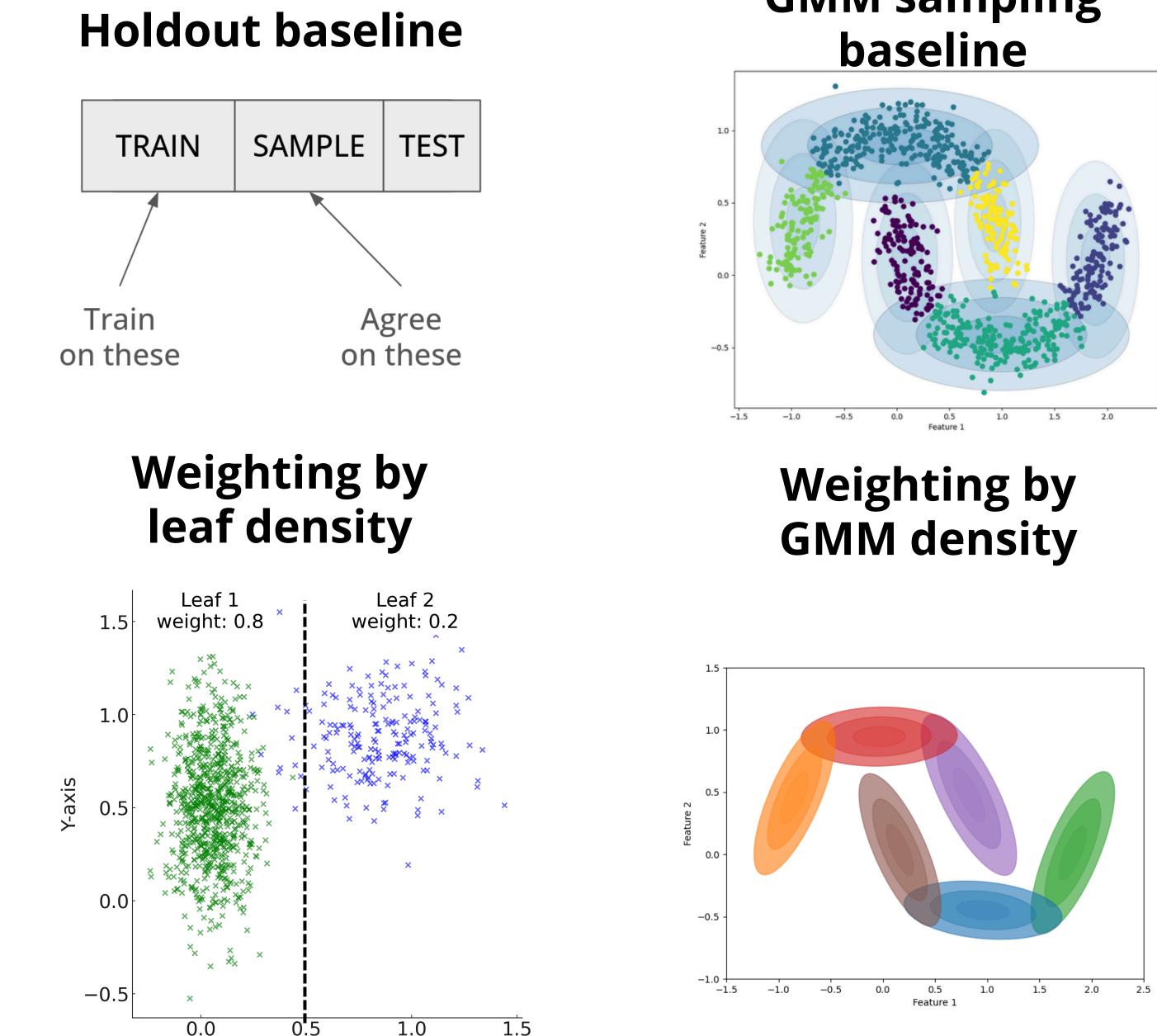
Solution

- Leverage density estimation of the data to weight FSR and enforce stronger agreement on parts of the domain with data and weaken in other places
- sampling baselines Add two for comparison

Improving performance of distributed learning through density ensimation

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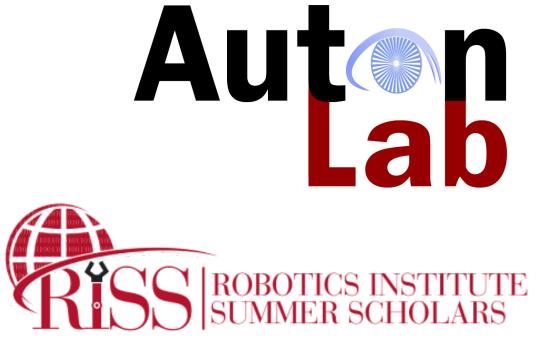
Method



Results

| dataset | central | holdout baseline | GMM sampling baseline | leaf density estimate | <u>function space</u> |
|----------|---------|---------------------|-----------------------------|--------------------------|-----------------------|
| mc16 | 0.77 | 0.76 | 0.72 | 0.62 | 0.72 |
| | (78.0) | (206.0) | (135.0) | (202.0) | (184.0) |
| mc32 | 0.76 | 0.73 | 0.70 | 0.59 | 0.61 |
| | (44.0) | (87.0) | (152.0) | (137.0) | (140.0) |
| mc64 | 0.64 | 0.65 | 0.62 | 0.57 | 0.59 |
| | (32.0) | (87.0) | (89.0) | (59.0) | (95.0) |
| diabetes | 0.78 | 0.70 | 0.56 | 0.60 | 0.58 |
| | (114) | (65.0) | (38.0) | (48.0) | (28.0) |
| glass | 0.63 | 0.21 | 0.28 | 0.31 | 0.39 |
| | (34.0) | (19.0) | (41.0) | (24.0) | (59.0) |
| iris | 0.96 | 0.31 | 0.89 | 0.94 | 0.94 |
| | (4.0) | (21.0) | (6.0) | (8.0) | (8.0) |
| vehicle | 0.68 | 0.35 | 0.32 | 0.43 | 0.43 |
| | (68.0) | (61.0) | (53.0) | (93.0) | (120) |
| wdbc | 0.92 | 0.61 | 0.87 | 0.87 | 0.81 |
| | (4.0) | (68.0) | (8.0) | (8.0) | (4.0) |
| digits | 0.85 | 0.85 | 0.18 | ? | 0.26 |
| | (123) | (123) | (~160) | (123) | (~160) |

X-axis



Discussion

- On synthetic datasets, weighting by data density significantly improves over base FSR approach and is close to central and holdout model performance
- On real-world datasets, the GMM density method shows a slight increase in performance in most bases and a more than doubles the score for digits dataset
- density estimate leads to a Good significant increase in performance

Future Work

- distributions Consider othei Gaussian and logistic
- Develop tools for choosing a estimate

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- The authors extend their heartfelt appreciation to the CMU RISS program team, particularly Rachel Burcin and Dr. John M. Dolan

References

[1] Almeida, Inês, and Joao Xavier. "Djam: Distributed jacobi asynchronous method for learning personal models." IEEE Signal Processing Letters 25.9 (2018): 1389-1392.

Table 1. **F1 score and (number of leaves)** of the trained decision trees for each proposed method and dataset

GMM sampling

GMM density <u>estimate</u> 0.77 (196.0) 0.76 (113.0) 0.65 (87.0) 0.58 (32.0) 0.34 (62.0) 0.95 (8.0) 0.42 (112.0)0.89 (4.0) 0.51 (~130)

| er | than |
|----|---------|
| £ | density |